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## PATENT SPECIFICATION

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## (54) RADIATION SCANNING SYSTEM

We, BARR AND STROUD LIMITED, a British Company, of Caxton Street, Anniesland, Glasgow, G13 1HZ, Great Britain, do hereby declare the invention, for which we pray that a patent may be granted to us, and the method by which it is to be performed, to be particularly described in and by the following statement:-

This invention relates to apparatus for use in a radiation scanning system and in particular to different forms of opto-mechanical reflectors which are used in the optical and/or infra-red waveband.

According to the present invention there is provided apparatus for use in a radiation scanning system comprising an objective device forming convergent radiation from a field of view, a radiation detector, and an optical scan means which is arranged to scan convergent radiation from said field of view across said detector, said scan means comprising:

a first drum which is rotatable about a first axis, a first set of optical members mounted on said first drum and defining a plurality of first planar reflective

a second drum which is rotatable about a second axis extending parallel to and spaced from said first axis, a second set of optical members mounted on said second drum and defining a plurality of second planar reflective surfaces, drive means for rotating said first drum sequentially to move each of said first

optical members through a first reflector station, and for rotating said second drum sequentially to move each of said second optical members through a second reflector station, wherein the first and second reflector stations are axially spaced, and, in use, convergent radiation from said field of view is directed by said objective device to enter said detector, after sequential reflection at said first and second reflector stations, in a cone of radiation having a stationary axis.

Conveniently, said drums each have the same number of planar reflective surfaces and are arranged for rotation at the same angular velocity in the same direction. Alternatively, said drums have different numbers of planar reflective surfaces and are arranged for asynchronous rotation in the same direction.

Embodiments of the present invention will now be described by way of example with reference to the accompanying drawings, in which:

Fig. 1 diagrammatically illustrates a first embodiment;

Fig. 2 is a plan view of Fig. 1; Fg. 3 is a diagram which is useful in understanding the principles underlying the 35 present invention;

Fig. 4 diagrammatically illustrates a second embodiment; Fig. 5 illustrates the second embodiment in greater detail;

Fig. 6 diagrammatically illustrates an optical equivalent using only a single rotating drum;

Fig. 7 illustrates a practical arrangement of a Fig. 6 system;

Fig. 8 diagrammatically illustrates a modification of the Fig. 6 system; Fig. 9 diagrammatically illustrates a third embodiment;

Fig. 10 illustrates a first modification of Fig. 9;

Fig. 11 illustrates a second modification of Fig. 9; and Fig. 12 shows a scanning system having 1st and 2nd directions of scan.

The first embodiment of radiation scanner illustrated in the drawings comprises a detector 10 and a rotary assembly 11 by means of which radiation from an objective lens 12 located in a field of view is scanned across the detector 10. The assembly 11

In the particular embodiment illustrated in Fig. 5 a drive shaft 21 driven by a drive motor (not shown) drives the outer drum 13 and, by way of a gear train, also drives the drum 16. The Fig. 5 embodiment also incorporates an optical imaging element 22 which focusses incident radiation onto the detector 10. In the event that the element 22, which may be either reflective or refractive, is of relatively short focal length the cone of radiation which forms the image of a particular point in a field of view may pivot significantly as the field is scanned and this effectively means that the radiation entering the detector does so at a variable angle of incidence. Thus, 'telecentricity' is lost. To correct for this phenomenon a modified form of rotational assembly may be provided wherein the inner and outer drums have differing numbers of mirrors and are rotated at differing speeds. It can be shown that substantial telecentricity and distortion-free scanning is achieved provided that the location of the detector is related to the radial magnitude of the two drums, the spacing of the rotation axes and the ratio of the number of mirrors. If the detector is located at a distance

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a from the axis 14 and the drum of radius  $r_1$  has  $n_1$  mirrors and the drum of radius  $r_2$  has  $n_4$  mirrors the required condition is:

$$2a \left[\frac{n_1}{n_2} - 1\right]^2 + 2d \left[\frac{n_1}{n_2}\right]^2 + r_2 \left[\frac{n_1}{n_2}\right]^2 - r_1 \left[\frac{2n_1}{n_2} - 1\right]^2$$

Returning to Fig. 3, arrangement G is such that the dimensions of the two drums are the same and they are both internally reflective, the reflective surfaces of one drum passing through the axis of rotation of the other drum. It can be shown that this arrangement can be simulated optically by the use of a roof reflecting arrangement, either in prism or mirror form located in a predetermined position within an internallyreflective drum. Specifically, the apex of the room should be located at a distance of half the drum radius from the axis of rotation. Consequently, the two rotating drums described with reference to Fig. 3 can be replaced with only a single rotating drum although this does not form a part of the present invention in combination with a stationary reflector, the arrangement being such that radiation is twice reflected from the rotating drum during each scan. This arrangement is illustrated diagrammatically in Fig. 6 where a drum 30 which is rotatable about an axis 31 carries a plurality of planar mirrors 32. Radiation from a field of view and rendered convergent by a lens 33 is reflected for a first time from a mirror 32 onto a stationary reflector 34 which is in the form of a pair of mirrors having their apex 35 lying parallel to the axis 31. After reflection from the reflector 34 the radiation is reflected for a second time from the same mirror 32 into the detector 10 which, to prevent obscuration, is imaged by relay optics 36 to a real image lying within the drum 30. The set of mirrors 32 effectively forms two sequences of reflective surfaces, the first sequence interrupting the radiation prior to reflection by the reflector 34 and the second sequence interrupting the radiation after reflection by the reflector 34.

A practical form of the embodiment of Fig. 6 is illustrated in Fig. 7 and comprises the drum 30 which is carried by a central hub 37 which is rotated by a belt drive 38. The detector 10, the relay optics 36 and the reflector 34 are all carried on a stationary frame 39 with the optics 36 being removable for the purpose of fitting lens systems of differing characteristics, such as is indicated at 36'. A chopper or blanking element 40 is arranged to intercept the radiation path to the detector 10 during those periods when there exists a confusion of scanned radiation, as described above. Fig. 7 also includes a focussing element 41.

In a modified arrangement of the system illustrated in Fig. 6 the drum is arranged to have two sets of planar mirrors arranged at different perpendicular distances from the axis of rotation of the drum. This is shown in Fig. 8 wherein incoming radiation is reflected from a mirror 42, forming part of a first set of mirrors, onto the reflector 34 and onto a mirror 43 forming part of a second set of mirrors. Thereafter the scanned radiation is relayed to the detector 10 by optics 36. With this arrangement it is possible to simulate drums of different diameters which facilitate the construction

of practical arrangements for folding of the radiation beam.

Telecentricity and distortion-free scanning is achieved when the apex of the roof the roof reflecting arrangement is located at half the mean radius of the two sets of planar mirrors.

In all of the arrangements described above the radiation enters and leaves the rotary assembly in an oblique fashion with respect to the axis of rotation. If it is desired that the radiation enter and/or leave the rotary assembly either parallel to or perpendicular to the rotational axis each plane mirrors may be replaced by a roof perpendicular to the rotational axis each plane mirrors may be replaced by a roof mirror roof prism. One example of this arrangement is shown in Fig. 9 wherein the rotary assembly 50 comprises a first drum supporting a plurality of identical mirror pairs 52. Radiapairs 51 and a second drum supporting a plurality of identical mirror pairs 52. Radiapairs 51 and a second drum supporting a plurality of identical mirror pairs 52. Radiapairs of pairs 52 and passes into the detector 10 in a direction normal to the axis 54.

Fig. 10 is the prism equivalent arrangement of Fig. 9, the reflective surface 53' being formed on a prism 53A, the mirror pairs 51' being formed on prisms 51A and the mirror pairs 52' being formed on prisms 52A. Fig. 11 shows an alternative arrangement of the prisms 51A and 52A which permits radiation to enter in the direction of the axis of rotation and to enter the detector 10 in a parallel direction.

All of the arrangements described above provide a scan of a field of view in one dimension only. To achieve a scan in a second dimension the arrangements of Figs. 1 to 8 may be utilised in combination with a 'flapper' mirror. Alternatively a sliding corner cube element may be utilised as will be described with reference to Fig. 12 or

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	in some cases it may be practical to angle successive mirrors with respect to the drum axis. The arrangements of Figs. 9 and 10 will provide a distortion-free scan in a secondary direction such as is required for a banded scanner if successive mirror pairs or roof prisms on one of the drums are displaced in a direction parallel to the axes of or roof prisms on one of the drums are displaced in a direction parallel to the axes of	5
5	rotation. This may also be done in the arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which is rotated about a central hub 61 by a belt arrangement comprises a drum 60 which a	10
10	stationary support 64 which carries a set of from a sliding corner cube 66 onto a mirror tion entering the arrangement is reflected from a sliding corner cube 66 onto a mirror 67 forming part of the drum 60. After reflection from the mirror 67 and the mirror 67 forming part of the drum 60. After reflection from the mirror 68. To	10
15	schieve scanning of the held of view in a second and a slideway 70 by means of carn and supported by a carrier 69 which is driven along a slideway 70 by means of carn and supported by a carrier 69 which in turn is driven through a gearing system from the follower arrangement 71 which in turn is driven through a gearing system from the motor 63 and thus is held in synchronism with the primary scanning movement	15
20	imparted by rotation of the drum 60.  The radiation scanners described above are of relatively simple mechanical construction and are capable of being driven at relatively high rotary speeds. The detector which is utilised will conveniently be in the form of a linear array of detector elements and the array may be arranged to lie parallel to or perpendicular to the direction of scan. In the even that the detector elements are scanned sequentially by the same part of the field of view it will be necessary to delay the output signals prior to summation.	20
		25
25	WHAT WE CLAIM IS:—  1. Apparatus for use in a radiation scanning system comprising an objective device forming convergent radiation from a field of view, a radiation detector, and an optical scan means which is arranged to scan convergent radiation from said field of view scan means which is arranged to scan convergent radiation from said field of view	
30	across said detector, said scan infants comprising.  a first drum which is rotatable about a first axis, a first set of optical members mounted on said first drum and defining a plurality of first planar reflective	30
35	surfaces, a second drum which is rotatable about a second axis extending parallel to and spaced from said first axis, a second set of optical members mounted on said second drum and defining a plurality of second planar reflective surfaces, drive means for rotating said first drum sequentially to move each of said first drive means for rotating said first effective station, and for rotating said second optical members through a first reflective station, and for rotating said second	35
40	drum sequentially to move each of said second optical members through a second reflector station, wherein the first and second reflector stations are axially spaced, and, in use, convergent radiation from said field of view is directed by said objective device to enter said detector, after sequential reflection at said first and second reflector stations, in a cone of radiation	40
45	having a stationary axis.  2. Apparatus as claimed in Claim 1, wherein the number of optical members in said first and second sets is the same and said drive means provide synchronous rota-	45
43	3. Apparatus as claimed in either preceding claim, wherein said first drum is an annular structure and said first set of optical members is mounted on the inner periannular structure and said first set of optical members is mounted on the inner periannular structure.	. 50
50	phery thereof with said planar renective surfaces inwardly  4. Apparatus as claimed in any preceding claim, wherein said second set of optical members is mounted on the outer periphery of said second drum with said planar reflective surfaces outwardly facing.  5. Apparatus as claimed in Claim 4, wherein said objective device focusses said	
	convergent radiation at said second renear and said detector	. 55
55	6. Apparatus as claimed in any preceding claim, which stands of said number of reflective surfaces each of which extends perpendicular to a radius of said first drum and is located at a perpendicular distance r <sub>1</sub> from the first axis of rotation, first drum and is located at a perpendicular distance r <sub>2</sub> from the first axis of rotation, first drum and is located at a perpendicular distance r <sub>3</sub> from the first axis of rotation,	
60	said second drum has $n_2$ number of reflective sinfacts can be second drum and is located at a perpendicular distance r <sub>2</sub> from the second axis of rotation, and the distance between the first and second axes in a plane perpendicular to said axes is d, and the detector is located at a distance a from the first rotational axis when measured in a plane perpendicular to the said axis such that the following condition holds:	60

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 $2a \left[\frac{n_1}{n_2} - 1\right]^2 + 2d \left[\frac{h_1}{n_2}\right]^2 + r_2 \left[\frac{n_1}{n_2}\right]^2 - r_1 \left[\frac{2n_1}{n_2} - 1\right]^2$ 

7. Apparatus as claimed in Claim 6, wherein  $n_1=n_2$  and said drive means is arranged to drive said drums at the same angular velocity in the same direction.

8. Apparatus as claimed in Claim 6, wherein n<sub>1</sub>=n, and said drive means is

arranged to drive said drums as synchronously in the same direction.

9. Apparatus as claimed in any one of Claims 1 to 5, wherein each said optical member has two planar reflective surfaces mutually disposed at right angles to each other.

10. Apparatus as claimed in Claim 9, wherein each optical member comprises a

prism on which said two planar reflective surfaces are located.

11. Apparatus for use in a radiation scanning system, and substantially as hereinbefore described by way of example with reference to any one of the embodiments illustrated in Figs. 1—5 or 9—11 of the accompanying drawings.

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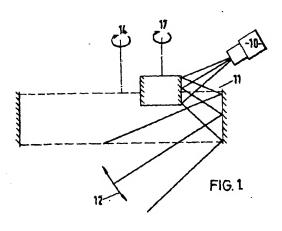
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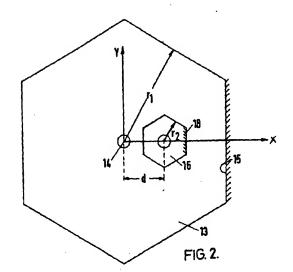
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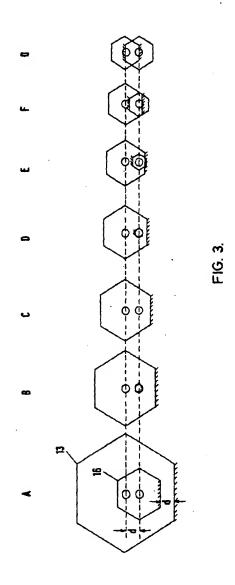
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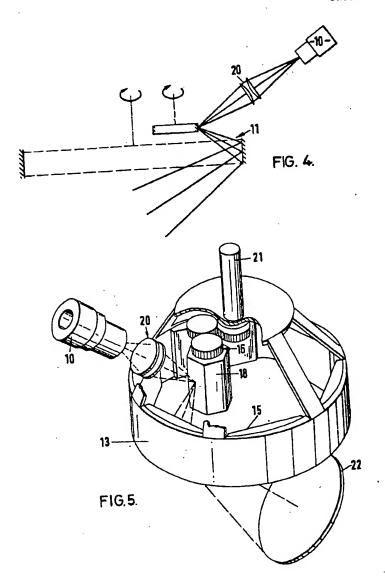




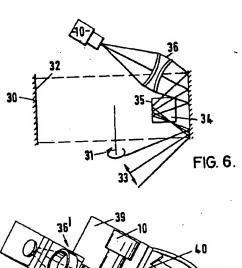
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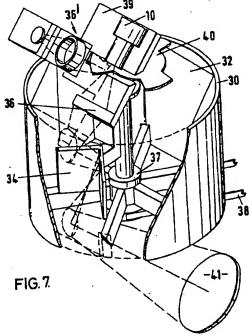


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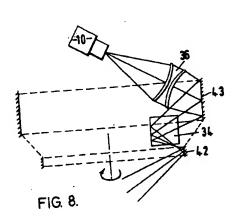
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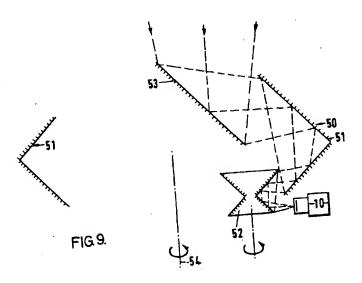




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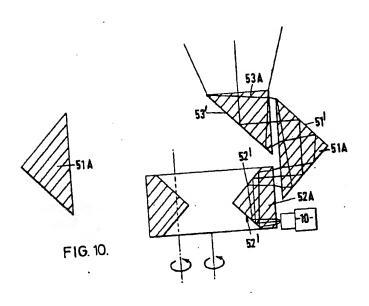
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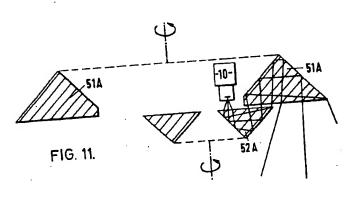




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